Sage and Linear Algebra Worksheet FCLA Section VR

Robert Beezer Department of Mathematics and Computer Science University of Puget Sound

Fall 2019

1 Vector Representations

It is easy to form vector representations of vectors in \mathbb{C}^n .

We get a nonstandard basis quickly from the columns of a nonsingular matrix. The keyword algorithm='unimodular' requests a matrix with determinant 1.

The columns of A become the "user basis" of a vector space.

```
B = A.columns()
V = (QQ^n).subspace_with_basis(B)
V
```

```
u = random_vector(QQ, n)
u
```

Now, we get values of the invertible linear transformation ρ_B with the Sage method .coordinate_vector() method of the vector space.

c = V.coordinate_vector(u)
c

The inverse linear transformation is also available as the .linear_combination_of_basis() method of the vector space.

```
round_trip = V.linear_combination_of_basis(c)
round_trip
```

And the automated check:

u == round_trip

Notice that this is something we could do "by hand" with just reduced row-echelon form. The coordinitization of u relative to the basis B is just a (unique) solution to a linear system.

```
aug = column_matrix(B + [u])
aug.rref()
```

The following stanza will always return True as we "coordinatize" and then use the coordinates to form a linear combination of the basis.

w = random_vector(QQ, n) x = V.coordinate_vector(w) y = V.linear_combination_of_basis(x) y == w

2 Abstract Vector Spaces

Sage does not implement abstract vector spaces. It presumes we have "nice" standard bases available and can apply an intermediate coordinatization ourselves.

Demonstration 1 In P_3 , the vector space of polynomials with degree at most 3, find the vector representation of $p = x^3 + x^2 + \frac{1}{2}x - \frac{33}{14}$ relative to the basis for P_3 :

$$B = \{5x^3 + 2x^2 + x + 1, -8x^3 - 3x^2 - x - 2, 7x^3 + 4x^2 + x + 2, -7x^3 + 3x^2 + x - 2\}$$

Hint: Coordinatize with respect to the basis $\{1, x, x^2, x^3\}$.

```
A = matrix(QQ, [[1, -2, 2, -2], [1, -1, 1, 1], [2, -3, 4,
3], [5, -8, 7, -7]])
B = A.columns()
B
```

B is a basis, since A is nonsingular.

```
A.is_singular()
```

Now coordinatize p.

```
p = vector(QQ, [-33/14, 1/2, 1, 1])
p
```

We'll get a coordinatization old-style.

```
aug = column_matrix(B + [p])
r = aug.rref()
r
```

Let's check to see if this is right and we can recover p.

```
soln = r.column(4)
round_trip = sum([soln[i]*B[i] for i in range(4)])
round_trip, round_trip == p
```

This work is Copyright 2016–2019 by Robert A. Beezer. It is licensed under a Creative Commons Attribution-ShareAlike 4.0 International License.